Compositional Development of Parallel Programs

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Overview

- Motivation
- Goals
- Programming Model
- Example
- Case Study
- Conclusions
- Current and Ongoing Work
- Future Directions

Motivation

- Optimization and adaptation of parallel programs is effort intensive
 - Different execution environments
 - Different problem instances
- Direct modification of complete application is effort intensive
- Maintenance and evolution of parallel programs is a complex task

Goals

- Order of magnitude productivity enhancement for program families
 - Develop parallel programs from sequential components
 - Reuse components
 - Enable development of program families from multiple versions of components
 - Automatic composition of parallel programs from components

Programming Model

Component Development

- Domain Analysis
- Component Development
- Encapsulate
- Program Instance Development
 - Analyze problem instance and execution environment
 - Identify attributes and attribute values
 - Identify data flow graph
 - Specify the program using the components and their interfaces

Component

Accepts interface (profile, transaction, protocol)

Sequential Computation

Requests interface (selector, transaction, protocol)

2D FFT Example

Steps for 2D FFT computation

- Partition given matrix row-wise
- Apply 1D FFT to each row of the partition
- Combine the partitions and transpose the matrix
- Partition transposed matrix row-wise
- Apply 1D FFT to each row of the partition
- Combine the partitions and transpose the matrix
- Transposed matrix is the 2D FFT of the original matrix

Fft_row	Gather_transpose
a) Domain: fft	a) Domain: matrix
b) Input: matrix	b) Function: gather
c) Element_type: complex	c) Element_type: complex
d) Algorithm: 1d-fft	d) Combine_by_row: true
e) Apply_per_row: true	e) Transpose: true
Distribute a) Domain: matrix b) Function: distribute c) Element_type: complex d) Distribute_by_row: true	Print a) Domain: print b) Input: matrix c) Element_type: complex

Fig. 2. Domain Analysis of the Components

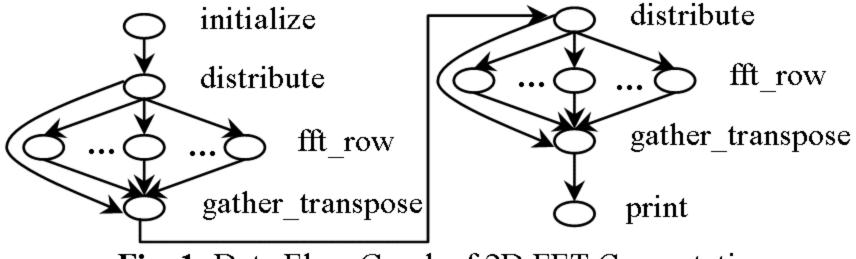


Fig. 1. Data Flow Graph of 2D FFT Computation

```
selector:
  string domain == "matrix";
                                                                   Requests
  string function == "distribute";
                                                                    interface
  string element_type == "complex";
  bool distribute_by_row == true;
                                                                       of
transaction:
                                                                    Initialize
  int distribute(out mat2 grid_re,out mat2 grid_im, out int n,
                 out int m, out int p);
protocol: dataflow;
profile:
  string domain = "matrix";
                                                                    Accepts
  string function = "distribute";
  string element_type = "complex";
                                                                    interface
  bool distribute_by_row = true;
                                                                       of
transaction:
                                                                    Distribute
  int distribute(in mat2 grid_re, in mat2 grid_im, in int n,
                  in int m, in int p);
protocol: dataflow;
```

Compilation Process

- Matching of
 - Selector and profile
 - Transactions
 - Profiles
- Matching starts from the selector of the start component
- Applied recursively to each matched components
- Output is a generalized data flow graph as defined in CODE (Newton '92)
- Data flow graph is compiled to a parallel program for a specific architecture

```
{selector:
  string domain == "fft";
  string input == "matrix";
                                                                   Requests
  string element_type == "complex";
  string algorithm == "Cooley-Tukey";
                                                                   interface
  bool apply_per_row == true;
                                                                   (partial) of
transaction:
                                                                   Distribute
  int fft_row(out mat2 out_grid_re[],out mat2
          out_grid_im[], out int n/p, out int m);
protocol: dataflow;
}index [ p ]
profile:
  string domain = "fft";
  string input = "matrix";
                                                                    Accepts
  string element_type = "complex";
  string algorithm = "Cooley-Tukey";
                                                                    interface
  bool apply_per_row = true;
                                                                       of
transaction :
                                                                   FFT Row
  int fft_row(in mat2 grid_re, in mat2 grid_im, in int n,
                   in int m);
protocol: dataflow;
```

```
selector:
  string domain == "matrix";
  string function == "gather";
                                                                  Requests
  string element_type == "complex";
                                                                   interface
  bool combine_by_row == true;
                                                                      of
  bool transpose == true;
transaction:
                                                                  FFT Row
  int gather_transpose(out mat2 out_grid_re,out mat2
                        out grid im, out int me);
protocol: dataflow;
profile:
  string domain = "matrix";
  string function = "gather";
  string element_type = "complex";
                                                                   Accepts
  bool combine by row = true;
                                                                   interface
  bool transpose = true;
                                                                      of
transaction:
                                                                  Gather Tr
  int get_no_of_p(in int n, in int m, in int p, in int state);
   >
                                                                   anspose
  int gather_transpose(in mat2 grid_re, in mat2 grid_im,
                         in int inst);
protocol: dataflow;
```

```
selector:
  string domain == "matrix";
  string function == "distribute";
                                                            Requests
  string element type == "complex";
                                                             interface
  bool distribute_by_row == true;
                                                             (partial)
transaction:
                                                               of
  % \{ exec_no == 1 \& \& gathered == p \} \}
                                                            Gather T
  int distribute(out mat2 out_grid_re,out mat2
                                                            ranspose
                   out_grid_im, out int m, out int n*p,
                   out int p);
protocol: dataflow;
```

Fast Multipole in Short

- Compute the Coulomb Energy of point charges in linear time
- Transforming the information about a cluster of charge into a simpler representation which is used to compute the influence of the cluster on objects at large distances by scaling all particles into hierarchy of cubes in different levels
- Can be extended and applied to astrophysics, plasma physics, molecular dynamics, fluid dynamics, partial differential equations and numerical complex analysis

Generalized Fast Multipole Solver – Matrix Version

- Many generalized *N*-body problems can be treated as multiple FMM problems which share the same geometry. This feature can be exploited by combining the generalized charges into a vector
- Generalized FMM is an extension of the FMM algorithm to multiple "charge types"
- More efficient FMM translation routines could be built using BLAS routines

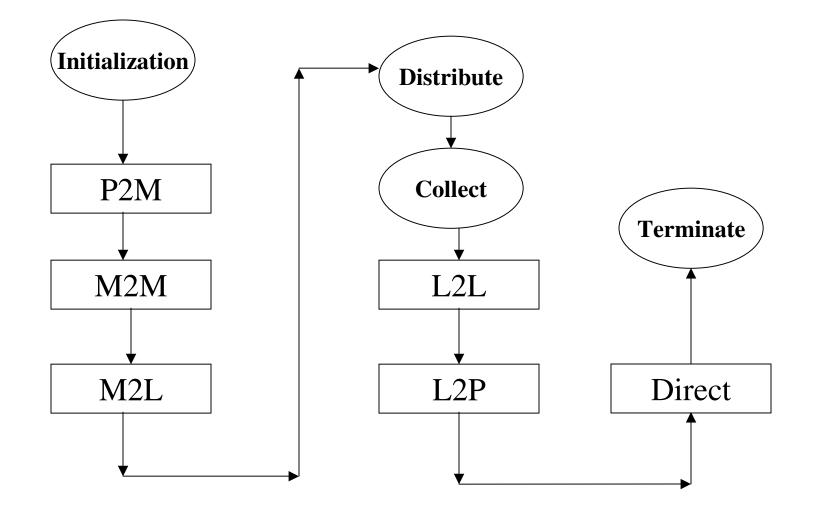
FMM Domain Analysis

- Six Translation Components
 - Particle charge to Multipole (finest partitioning level)
 - Multipole to Multipole (between all partitioning levels, from the finest to the coarsest)
 - Multipole to Local (all partitioning levels)
 - Local to Local (between all partitioning levels)
 - Local to Particle potential and forces (finest partitioning level)
 - Direct Interaction (finest partitioning level)
- Two Utility Components
 - Distribute Distribute Pre-Calculated Local Coefficient matrices according to Interaction list
 - Gather Gather Local coefficients

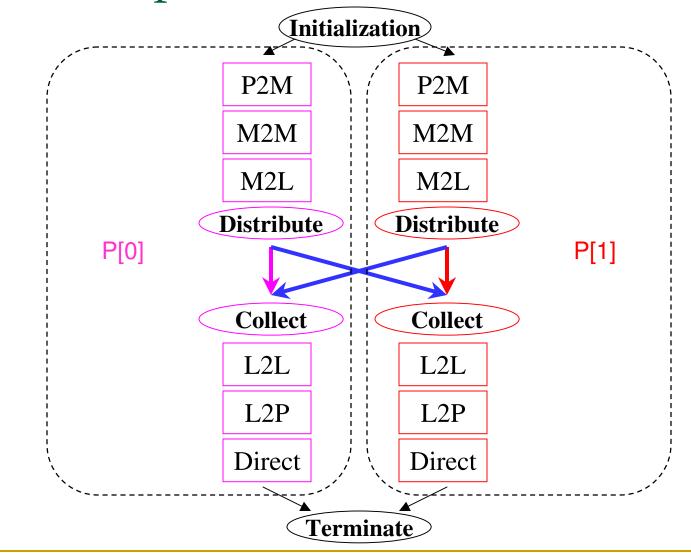
Space-computation Tradeoffs For Matrixstructured Formulation of the FMM Algorithm

- Simultaneous computation of cell potentials for multiple charge types
- Use of optimized library routines for vector-matrix and matrix-matrix multiply
- Loop interchange over the two outer loops to improve locality

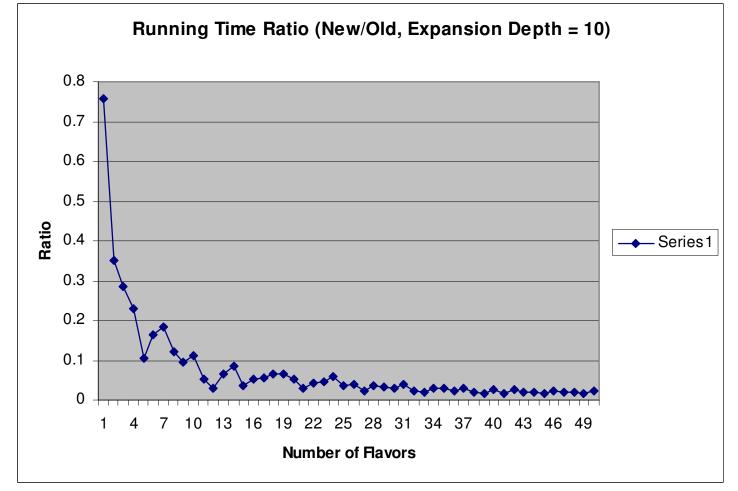
Flow Graph for Sequential FMM



Flow Graph for The Parallel Version



Sequential Running Time - New/Old WRT number of charge types



Conclusions

- Effort in domain analysis is not trivial
- Suitable for
 - Large applications that are to be optimized for several different execution environments
 - Large applications that are expected to evolve over a substantial period of time
 - Large applications with multiple instances
- Competitive program performance

Current and Ongoing Work

- Implement evolutionary performance models of programs through composition of components
 - Abstract components
 - Concrete components
 - Performance model for specific architecture
- Componentize hp-adaptive finite element code and Method of Lines (MOL) code

Future Directions

- Combine with dynamic linking runtime system based on associative interfaces [Kane '02]
- Implement more powerful precedence and sequencing operators for state machine specifications
- Integrate with Broadway [Guyer/Lin '99] annotational compiler to overcome "many components" problem