

Load Elimination in the Presence of Side-Effects, Concurrency and Precise Exceptions

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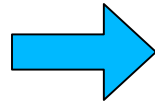
Motivation

- Frequent occurrence of **path-expressions** in OO programs:

```
l1 = o.f1.f2
```

```
...
```

```
l2 = o.f1.f2
```



```
t1 = ld(o, f1);
```

```
t2 = ld(t1, f2);
```

```
l1 = t2;
```

```
...
```

```
t3 = ld(o, f1);
```

```
t4 = ld(t3, f2);
```

```
l2 = t4;
```

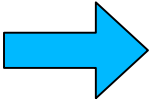
- Large number of (indirect) memory accesses
- Irregular access patterns (pointer-chasing)

Load elimination

Goal: Reduce # of memory accesses

“Promote” heap to local vars / registers

```
t1 = ld(o, f1);  
t2 = ld(t1, f2);  
l1  = t2;  
...  
t3 = ld(o, f1);  
t4 = ld(t3, f2);  
l2  = t4;
```



```
t1 = ld(o, f1);  
t2 = ld(t1, f2);  
l1  = t2;  
...  
l2  = t2;
```

Implementation for Java must consider ...

- Control- and data-flow
- Side-effects at call sites
- Precise exceptions
- Multi-threading

Multi-threading (1/3)

Original program:

```
s1, s2 = 0;    // shared
l1, l2, l3 = 0; // local to thread1

// thread 1          // thread 2
l1 = ld(s1);        st(s1, 1);
l2 = ld(s2);        st(s2, 1);
if (l2 != 0) {
    l3 = ld(s1);
}
```

Possible results : (l2, l3)

- SC: { (0, 0), (1, 1) }
- JC : { (0, 0), (1, 1), (1, 0) }

Subset correctness [Lee et. al. PPOPP 99]:

- Results of optimized programs must be in that set.

Multi-threading (2/3)

Optimized (load-elimination):

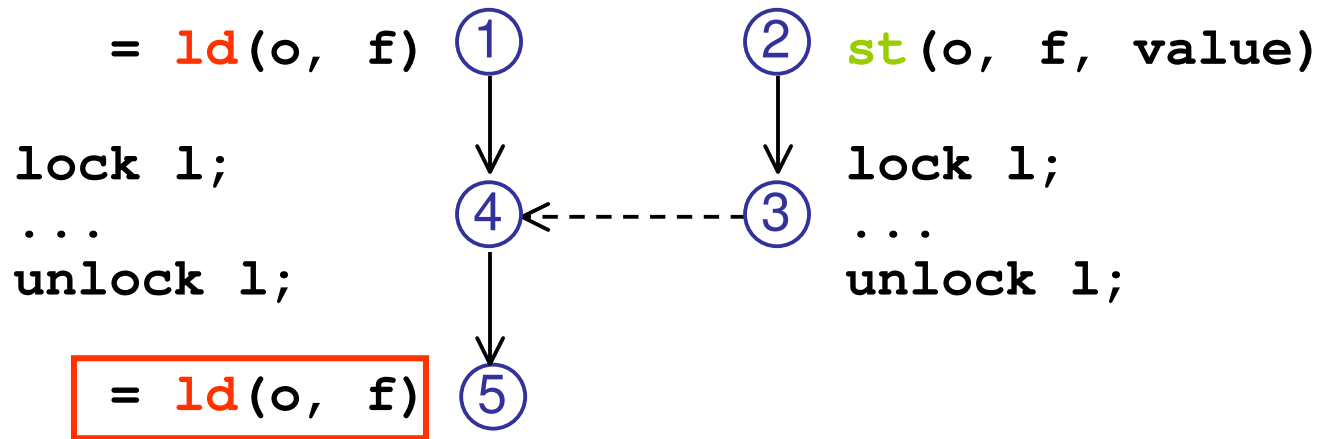
```
// thread 1           // thread 2
11 = ld(s1);          st(s1, 1);
12 = ld(s2);          st(s2, 1);
if (12 != 0) {
    13 = 11;
}
```

- | optimized | ! | original |
|------------------------------------|-----------------|------------------------------|
| • SC: $\{(0, 0), (1, 0), (1, 1)\}$ | $\not\subseteq$ | $\{(0, 0), (1, 1)\}$ |
| • JC: $\{(0, 0), (1, 0), (1, 1)\}$ | \subseteq | $\{(0, 0), (1, 0), (1, 1)\}$ |

- Correctness depends on memory model
- Access to `s1`, `s2` not “correctly synchronized”

Multi-threading (3/3)

- Synchronization “kills”:

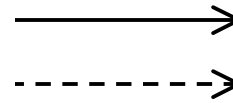


Must not be optimized!

program order

synchronization order

execution / causal order



consistency

- Similar: access to `volatile` variable “kills”.
- Criterion for correct optimization of Java.

2 Strategies ...

... to determine the absence of “killing” interference:

Strategy 1: **Synchronization kills**

- + simple, all fields, all accesses treated equally
- only correct for Java Consistency (JC)
- optimization potential not fully exploited

Strategy 2: **Exploit synchronization information**

- Aggressive optimization of thread-local and shared non-conflicting data
- No optimization of shared conflicting data
- + independent of memory model (correct for SC)
- needs concurrency and side-effect info

Procedure

- Whole program analysis
 - Side-effect analysis
 - Conflict analysis (Strategy 2)
- Intra-procedural load-elimination
 - based on SSA-PRE-based [Chow et. al., PLDI 97]
 - lexical equivalence of path expressions
 - Extensions that account for
 - side-effects
 - precise exceptions
 - concurrency (Strategy 2)

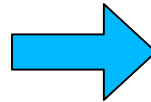
Conflict analysis

- Criteria for absence of a conflict?
 1. object is stack/thread-local
 2. accesses between NEW and orderly ESCAPE
 3. accesses before all STARTs
 4. accesses after all JOINs
 5. common protection through a unique lock
- Enhanced and improved version of [PraunGross PLDI03]

Strategy 2: Aggressive optimization

Absence of conflict on object o and field f allows for **aggressive optimization** across synchronization statements:

```
l1 = ld(o, f);  
lock l;  
...  
unlock l;  
l2 = ld(o, f);
```



```
l1 = ld(o, f);  
lock l;  
...  
unlock l;  
l2 = l1;
```

Reasoning:

- If o is not conflicting, then ...
- ... lock l is not involved in protecting o

Evaluation

- Application and library (GNU 2.96)
- Configurations:

(orig) no load elimination

(A) basic (call and synchronization kill)

(B) side-effect + synchronization-kills

(C) side-effect + conflict info

(D) side-effect + “perfect” synchronization

Strategy 1

Strategy 2

Optimized expressions (compile-time)

	(B) %	(C) %	(D) %
moldyn (*)	109.3	37.3	118.0
montecarlo (*)	128.9	142.7	149.1
mtrt (*)	192.0	202.6	210.9
tsp (*)	121.2	127.8	132.2
compress	126.7	146.6	146.6
db	123.1	176.2	176.2
jess	120.6	184.2	184.2
avg.	131.7	145.3	159.6

(*) multi-threaded **Strategy 1** **Strategy 2**

Percentage of eliminated expressions
basic configuration (A) = 100%.

Eliminated accesses (runtime)

	(A) %	(B) %	(C) %
moldyn (*)	41.1	41.1	14.6
montecarlo (*)	55.6	66.1	70.3
mtrt (*)	0.6	9.1	9.1
tsp (*)	25.6	25.3	25.0
compress	21.5	29.3	30.1
db	11.9	11.9	32.7
jess	17.4	17.4	17.8
avg.	23.4	28.6	28.5

(*) multi-threaded

Strategy 1 Strategy 2

Percentage of eliminated accesses
un-optimized (orig) = 100%.

Related work

- SSAPRE: Chow et. al. [PLDI 97]
- Load reuse analysis: Bodik et al. [PLDI 99]
- Register promotion by sparse PRE of loads and stores: Lo et al. [PLDI 98]
- Concurrent SSA for SPMD programs: Lee, et. al. [PPoPP 99]
- PRE-based load elimination for Java: Hosking et. al. [SP&E 2001]

Concluding remarks

- Load elimination is effective: up to 55% (avg. 25%) fewer loads than in the original program.
- Side-effect information reduces the number of loads on avg. by another 5%.
- Simple load elimination requires a weak memory model for correctness.
- Accurate information about concurrency can...
 - ... make the optimization independent of the MM
 - ... enable aggressive opt. across synchronization stmts.

Thank you for your attention.

Eliminated accesses (runtime)

	(orig) 100% mio. accs	(A) %	(B) %	(C) %
moldyn (*)	1651.3	58.9	58.9	85.4
montecarlo (*)	478.6	44.4	33.9	29.7
mtrt (*)	366.9	99.4	90.9	90.9
tsp (*)	899.0	74.4	74.7	75.0
compress	2423.5	78.5	70.7	69.9
db	446.6	88.1	88.1	67.3
jess	323.5	82.6	82.6	82.2
avg.		76.6	71.4	71.5

(*) multi-threaded

Strategy 1 Strategy 2